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MARKS-70

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# SARDARPATEL UNIVERSITY VVNAGAR

B.Sc.(6<sup>th</sup> SEM.) ELECTRONICS 17th July -2021 EXAMINATION

### 8-BIT MICROPROCESSOR PROGRAMMING AND APPLICATION-II SUB.CODE-US06CELE23

TIM	MARKS-70					
-			[10]			
Q-1	Choose correct answer	(aut gate) inoithius orgens and				
1.	HLT is instruction					
	(A) one byte	(C) three byte	parallemil			
77.013	(B) two byte	(D) none of above				
2.	is conditional jump in	struction.	- Sei			
	(A) JNC	(C) JMP 2030	A. P. Seien			
	(B) MOV A,B	(D) All of above	1/2/			
3.	An up counter counts in	(6) 1 1 1 1 1 1 1	LIBRAR			
	(A) ascending	(C) both A and B	7			
	(B) descending	(D) none of above				
4.		fter execution of ANI F0 H, the contain of	N. Nag			
	accumulator is	to interest V projetica someon to make not	l seleve at l			
	(A) 93 H	(C) 03 H				
	(B) 39 H	(D) 30 H				
5.	Looping and counting techn	iques are used to design and				
	(A) counter ,time delay	(C) repeating, exiting				
	(B) nesting, subroutine	(D) debugging, indexing				
6.	The decimal equivalent of F	A <sub>H</sub> is				
	(A) 250	(C) 235				
	(B) 251	(D) 255				
7.	program is used to count event.					
	(A) Counter	(C) Stacking				
	(A) Counter (B) Time delay	(D) none of above				
8.	Rotate accumulator Left ins	truction is				
0.	(A) RAR	(C) RLC				
	(B) RAL	(D) none of above				
9.	To set the carry flag					
9.	(A) XTHL	(C) CMC				
	(B) PCHL	(D) STC				
10.	POP H isbyte instruc					
10.	(A) one	(C) three				
	(B) two	(D) four				
	(B) two	(1) 1041				
Q-2	Fill in the blank		[08]			
1.	DAA instruction full name	e is				
2.	Down Counter program is u	sed to count in sequence.				
3.	Maximum time delay using single register program is					
4.	Out instruction is type of	instruction.				

#### True or False

- 5. TRAP interrupt is Maskable.
- **6.** RST 7.5 has highest priority interrupt signal in 8085 microprocessor.
- 7. XCHG instruction of 8085 exchanges the content of BC and DE register pair
- **8.** Programme counter is 16-bit register in 8085 microprocessor.

#### Q-3 Short answer type question. (any ten)

- 1. Define programme and software.
- 2. Briefly explain EI and DI.
- 3. Define T-state in 8085 μp.
- 4. Explain instructions: LHLD and ADC M
- 5. Which instructions are used to store and retrieve data from STACK?
- 6. Briefly explain CALL and RET instruction.
- 7. Write full name of ASCII code.
- 8. Write a program to load 9D H in register D, multiply 9D H by 2 using rotate instruction, and specify the result.
- 9. What do you mean by debugging in 8085 μp?
- 10. Draw the flow chart of counter and time delay using single register.
- 11. State different technique of debugging a program.
- 12. State different pins of interrupt control section of 8085 system.

### Q-4 Long answer questions(attempt any 4)

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- 1. Discuss different conditional and non conditional CALL and RETURN instructions with illustrations.
- 2. Write a program to count from 0 to 9 with 5 msec. time delay. At the count of 9 the counter should reset to zero and repeat the sequence continuously .Take the clock frequency is 1MHz and no. of T-state= 15 .Draw its flowchart also.
- 3. A set of three packed BCD number stored in memory locations starting at XX50 H. the seven segment code of digit 0 to 9 are stored in memory location starting at XX70 H. write a main programme and two subroutine to unpacked BCD number and select an appropriate seven segment code for each digit. The codes should be stored in the output buffer memory.
- Write a programme to convert two digit BCD number stored in memory location to its equivalent binary number.
- A set of five packed BCD number is stored in memory location stating at XX70 H. Write a program with subroutine to add all these numbers in BCD, if carry is generated save it in register B after adjusting it for BCD.

  Write second subroutine to unpack the BCD sum and stored them in output
  - buffer memory starting at XX60 H.
- Draw 8085 up vectored interrupt diagram and discuss it in detail.
  Describe following advanced instructions of 8085 up
  - (a) SHLD (b) ADC R (C) CMC
- 8. Discuss DAC and ADC concept in microcontroller.

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